

# Structure-measure: A New Way to Evaluate Foreground Maps

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ICCV 2017 (Spotlight)

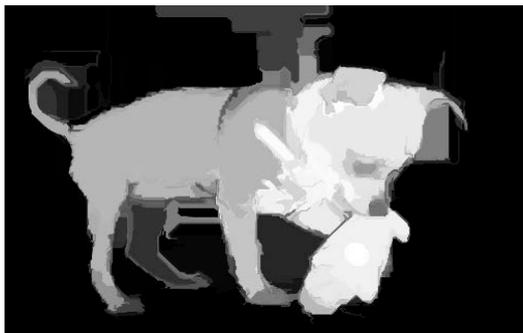
1



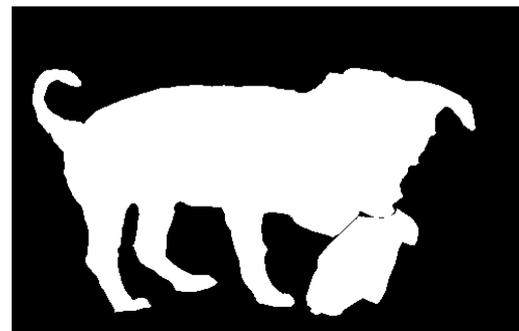
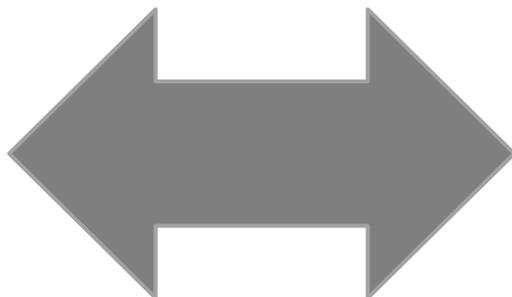
2



# Goal



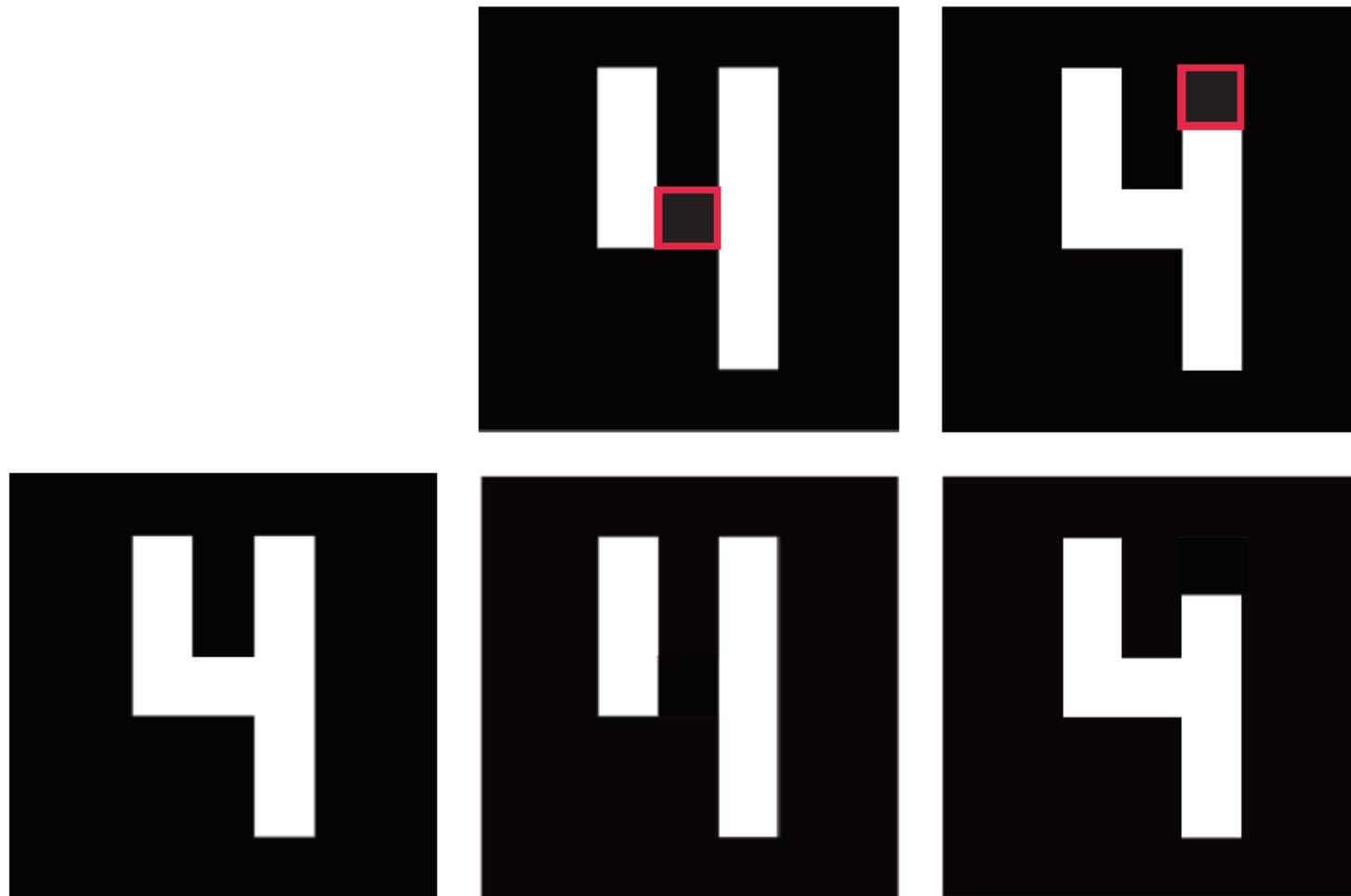
Similarity?



Ground Truth (GT)

Foreground map (FM)

# Pixel-wise based measures (AP, AUC)



(a) GT

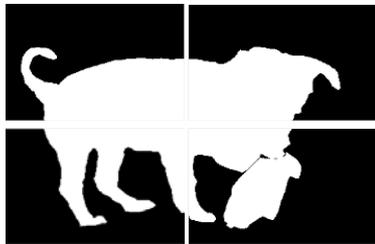
(b) FM1

(c) FM2

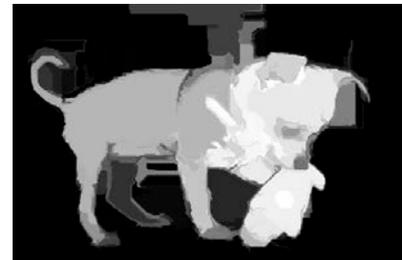
# Motivation



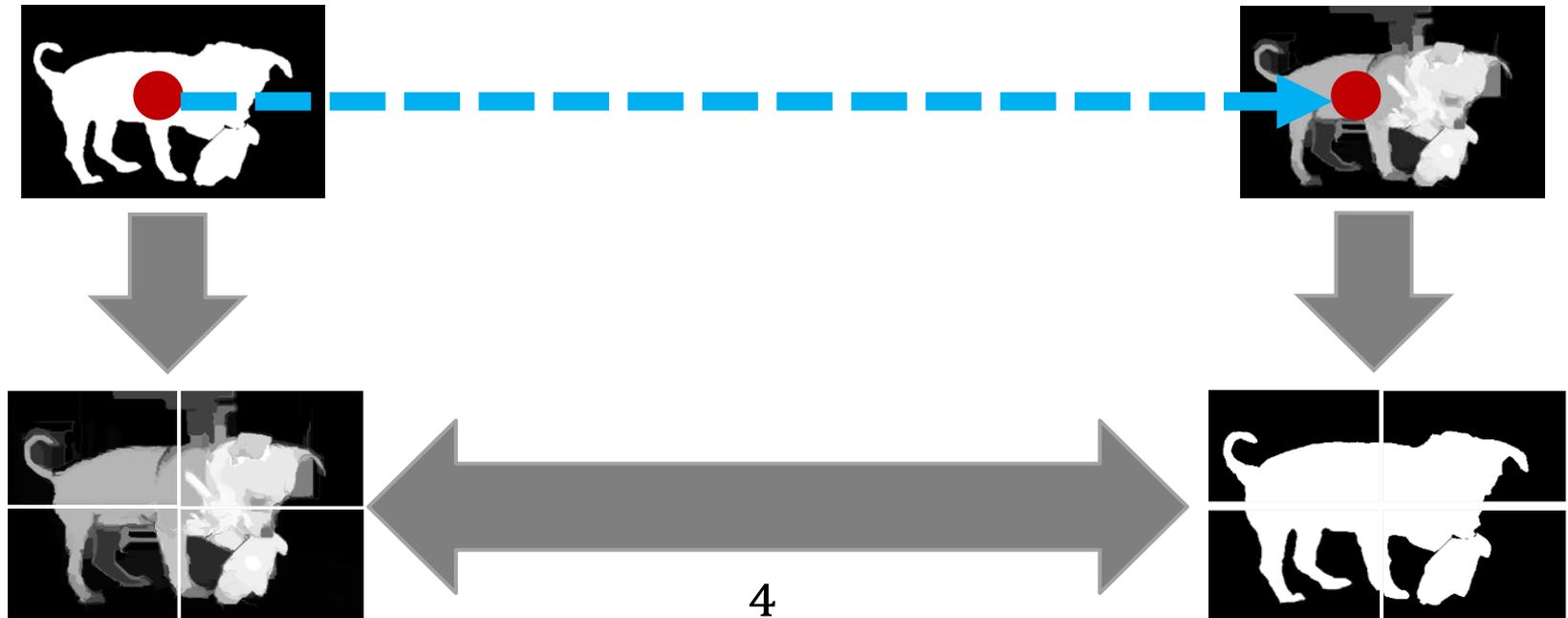
- **Region**  
structure consistency  
of **object-parts**;



- **Object**  
**uniformly** distributed;  
**contrast** sharply;



# Region-Level

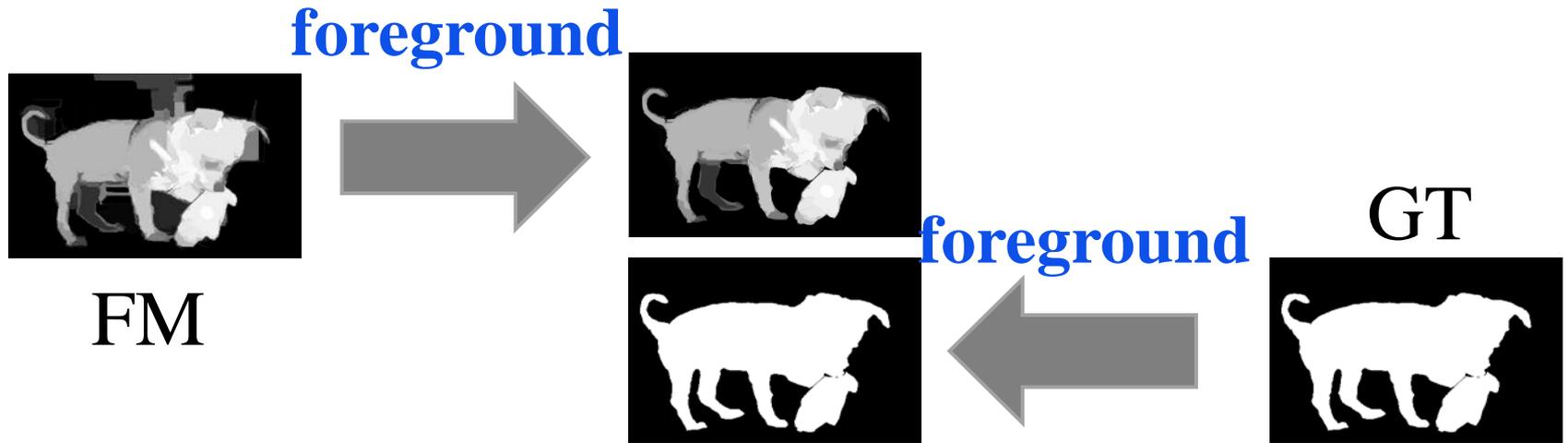


$$S_{region} = \sum_{j=1}^4 w_j * ssim_j$$



Image quality assessment: from error visibility to structural similarity, IEEE TIP 2004, Z Wang, AC Bovik et. al.

# Object-Level: foreground



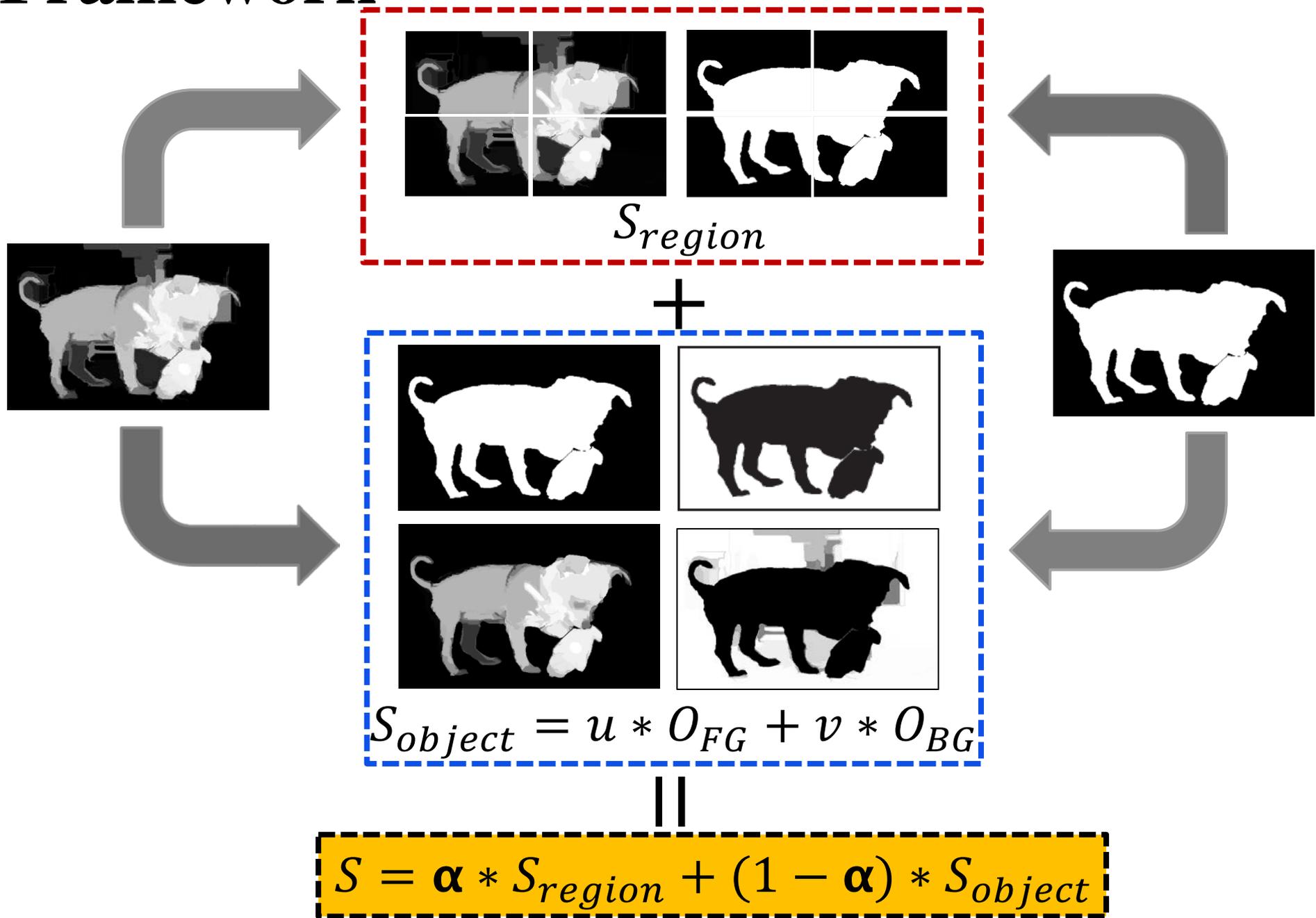
$$D_{FG} = \frac{(\bar{x}_{FG})^2 + (\bar{y}_{FG})^2}{2\bar{x}_{FG}\bar{y}_{FG}} + \lambda * \frac{\sigma_{x_{FG}}}{\bar{x}_{FG}}$$

**contrast**                      **uniform**

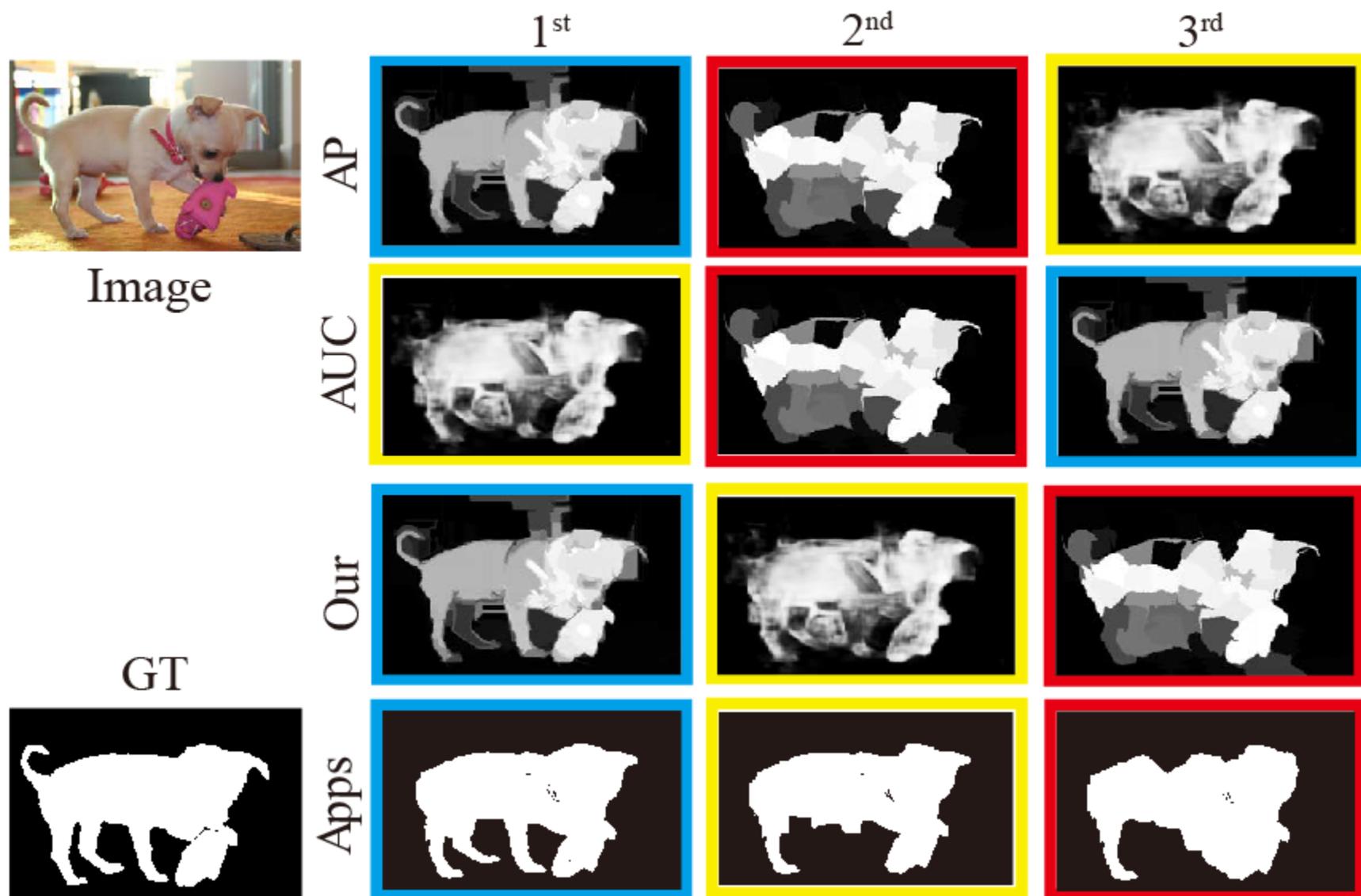
$$O_{FG} = \frac{1}{D_{FG}}$$

**S-measure**

# Framework

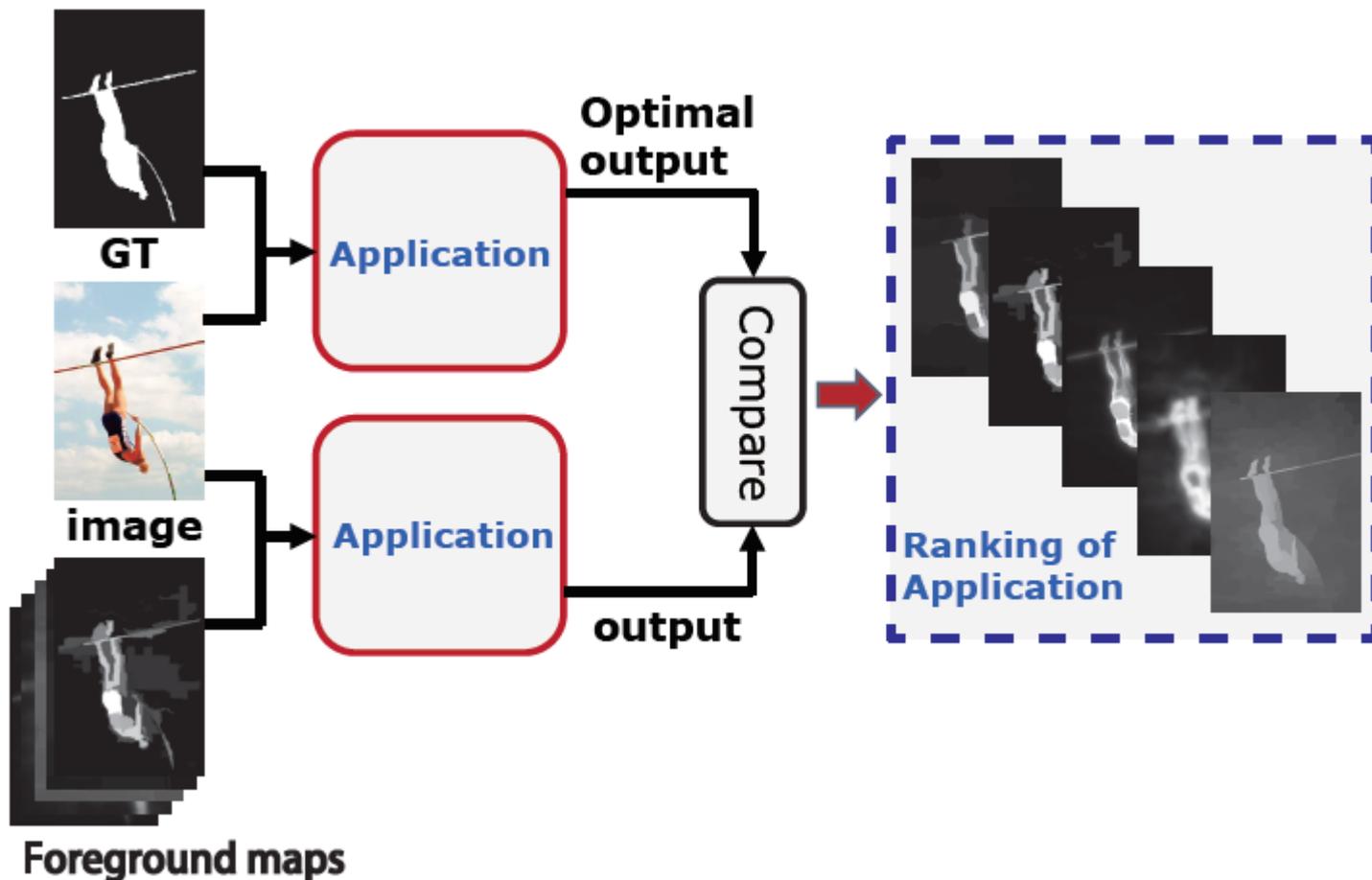


# Ranking example



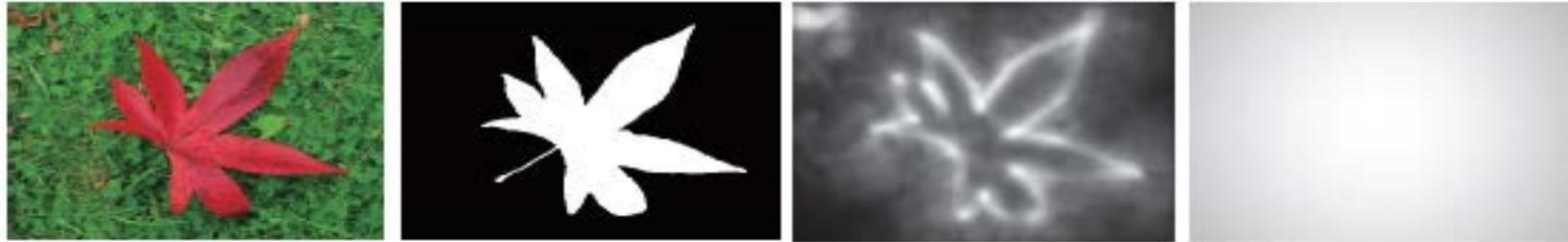
# Meta-Measure1

- ▶ Agree with the **application**: Saliency Cut



# Meta-Measure-2

- ▶ Prefer a good result over an **Generic** result



(a)Image

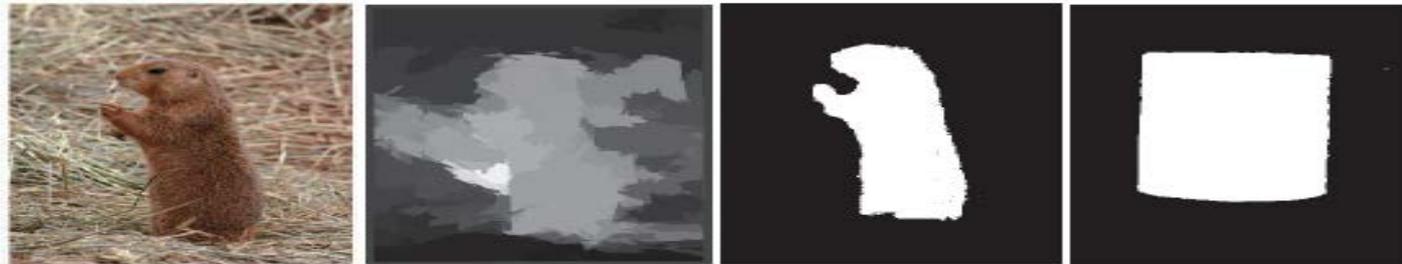
(b)GT

(c)FM1

(d)Generic

# Meta-Measure-3

- ▶ **WRONG** ground-truth decrease score



(a)Image

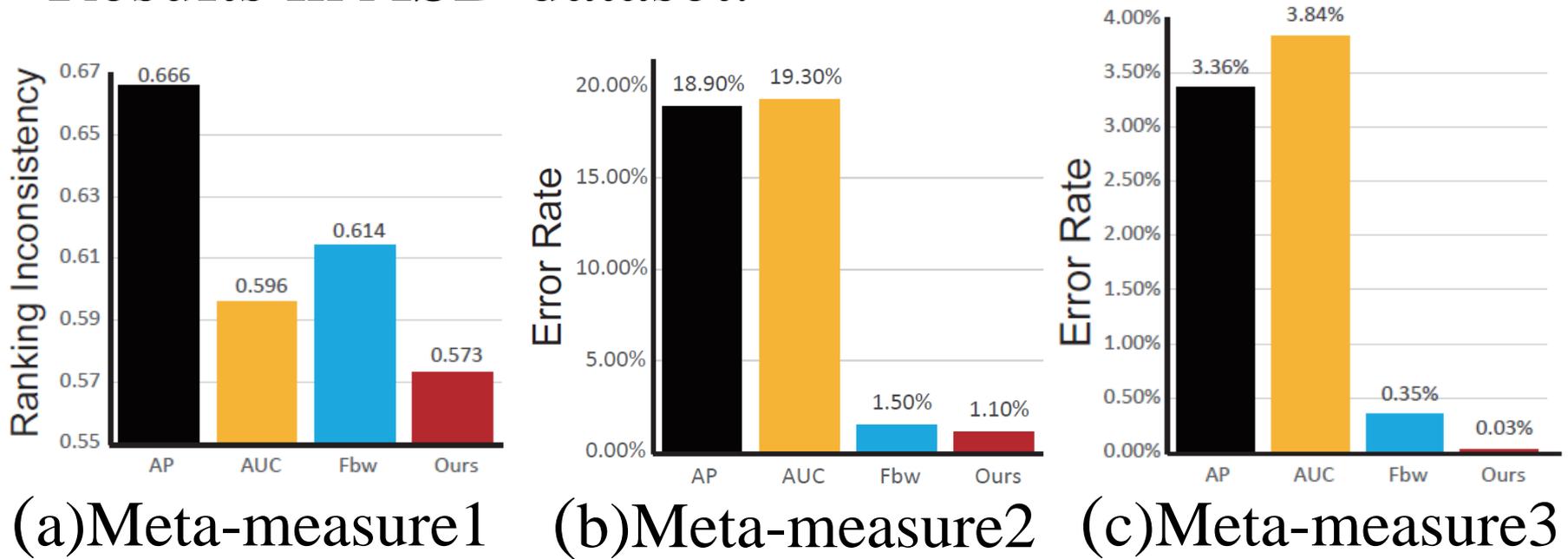
(b)FM

(c)GT

(d)WRONG GT

# Results

## ► Results in ASD dataset.

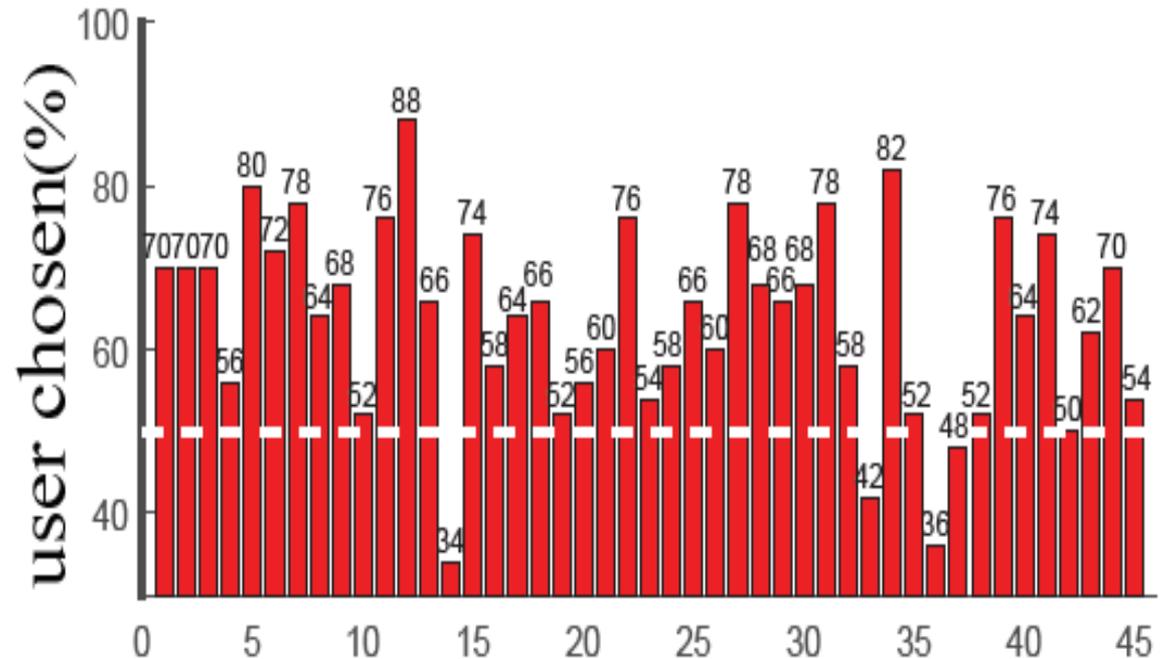
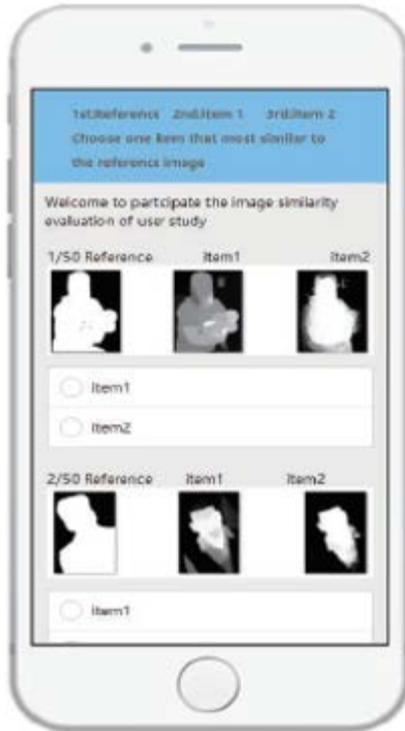


## ► Results in other popular datasets.

	PASCAL-S [31]			ECSSD [47]			SOD [37]			HKU-IS [27]		
	MM1	MM2(%)	MM3(%)	MM1	MM2(%)	MM3(%)	MM1	MM2(%)	MM3(%)	MM1	MM2(%)	MM3(%)
AP	0.452	12.1	5.50	0.449	9.70	3.32	0.504	9.67	7.69	0.518	3.76	1.25
AUC	0.449	15.8	8.21	0.436	12.1	4.18	0.547	14.0	8.27	0.519	7.02	2.12
Fbw	0.365	7.06	1.05	0.401	<b>3.00</b>	0.84	0.384	16.3	0.73	0.498	0.36	0.26
Ours	<b>0.320</b>	<b>4.59</b>	<b>0.34</b>	<b>0.312</b>	3.30	<b>0.47</b>	<b>0.349</b>	<b>9.67</b>	<b>0.60</b>	<b>0.424</b>	<b>0.34</b>	<b>0.08</b>

# Meta-Measure 4

- ▶ Agree with the **human ranking**.



**~62% viewer preferred the map chosen by our measure.**

# Thanks!

<http://dpfan.net/smeasure/>

**S-measure**